

*Series: IDAM[®] Servo Drive E
Digital Motor Drive - DMD-078.12*



- Integrated amplifiers for 8 single-phase motors, 4 two-phases motors or 4 three-phases motors or combinations of them in one device
- Position feedback for Hall and optical measurement systems
- Continuous current: 7 A_{rms} per phase
- DC link voltage up to 120 V_{DC}
- Field bus: EtherCAT[®]

■ Features

Digital Motor Drive DMD-078.12 was developed for digital controlling the current of multi-axes motor systems. Up to 8 independent coil systems can be driven. The high-speed control algorithm with a current controller sample time of $25 \mu\text{s}$ enables highly dynamic positioning tasks for ironless or low-induction motors. The process data are exchanged via EtherCAT[®] for very fast interconnection between drive and PLCs/NCs. Digital Motor Drive DMD-078.12 can supply digitized encoder signals to the superposed controller system. Very fast control loops can thus also be closed via the bus. Two power supplies are needed to power the controller, the logic supply of 24 V and the DC link power supply with up to $120 V_{\text{DC}}$.

The firmware is divided into:

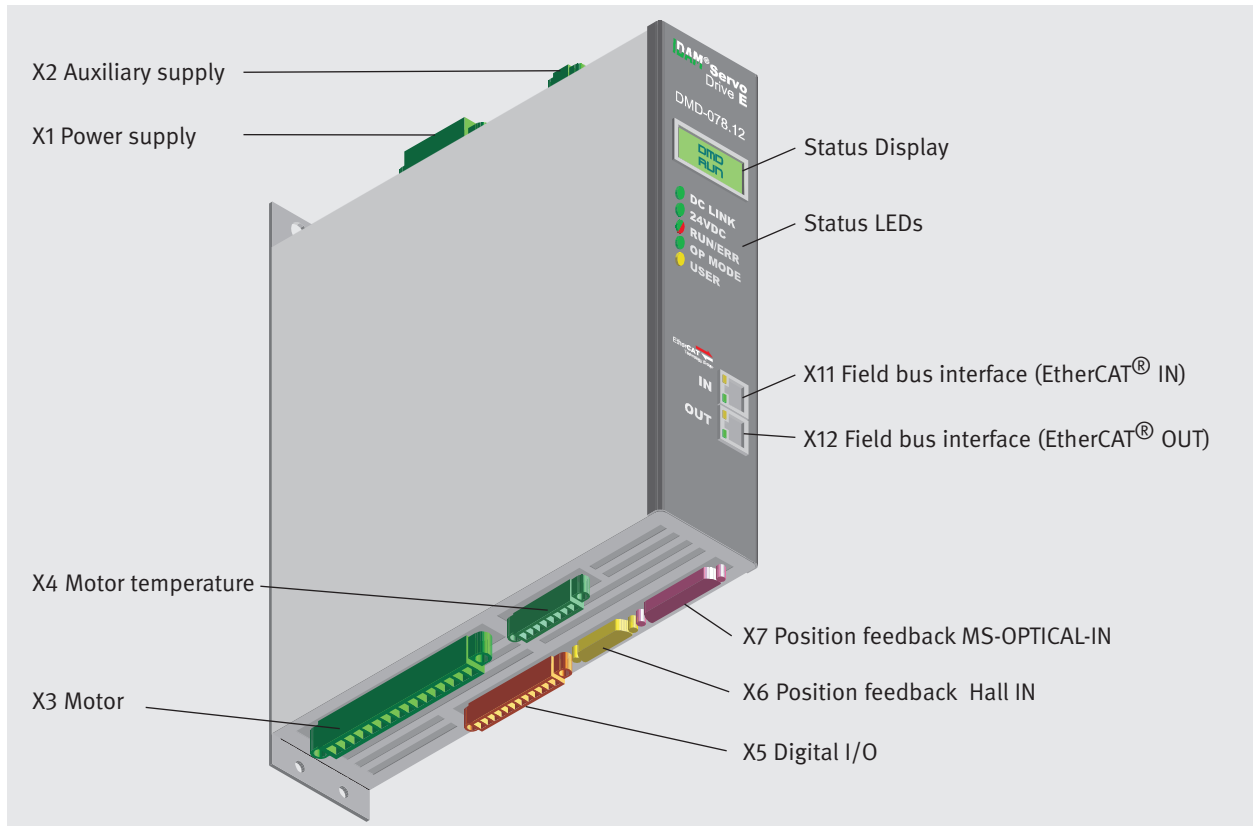
- Current loop controller
- PWM unit
- I^2t monitoring
- Motor temperature monitoring
- Heat sink temperature monitoring
- Controlling of all input analogue digital converters
- Digital I/O processing
- Field bus data processing via EtherCAT[®]
- Position interpolation for optical incremental feedback system (optical lattice)

The hardware is unitized into:

- Discrete power section with current sensing
- 2 x 10/100 MBit Ethernet port
- Encoder interface for HALL feedback system (3 axes)
- Encoder interface for optical feedback system (3 axes)
- Digital I/O



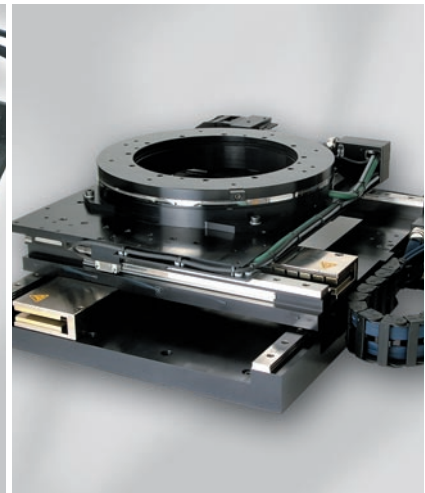
■ Functionality



Servo Planar System



LDS49 with Pneumatic Collet Chuck



3-Axes Positioning System: Open Frame

DMD-078.12 is a multi-axis power amplifier which can control synchronous 1-phase motors, 2-phase motors and/or 3-phase motors. For example: systems consisting of a 3-phase rotary table, a 2-phase linear cross table and two force controlled voice coil motors can be controlled by one DMD.

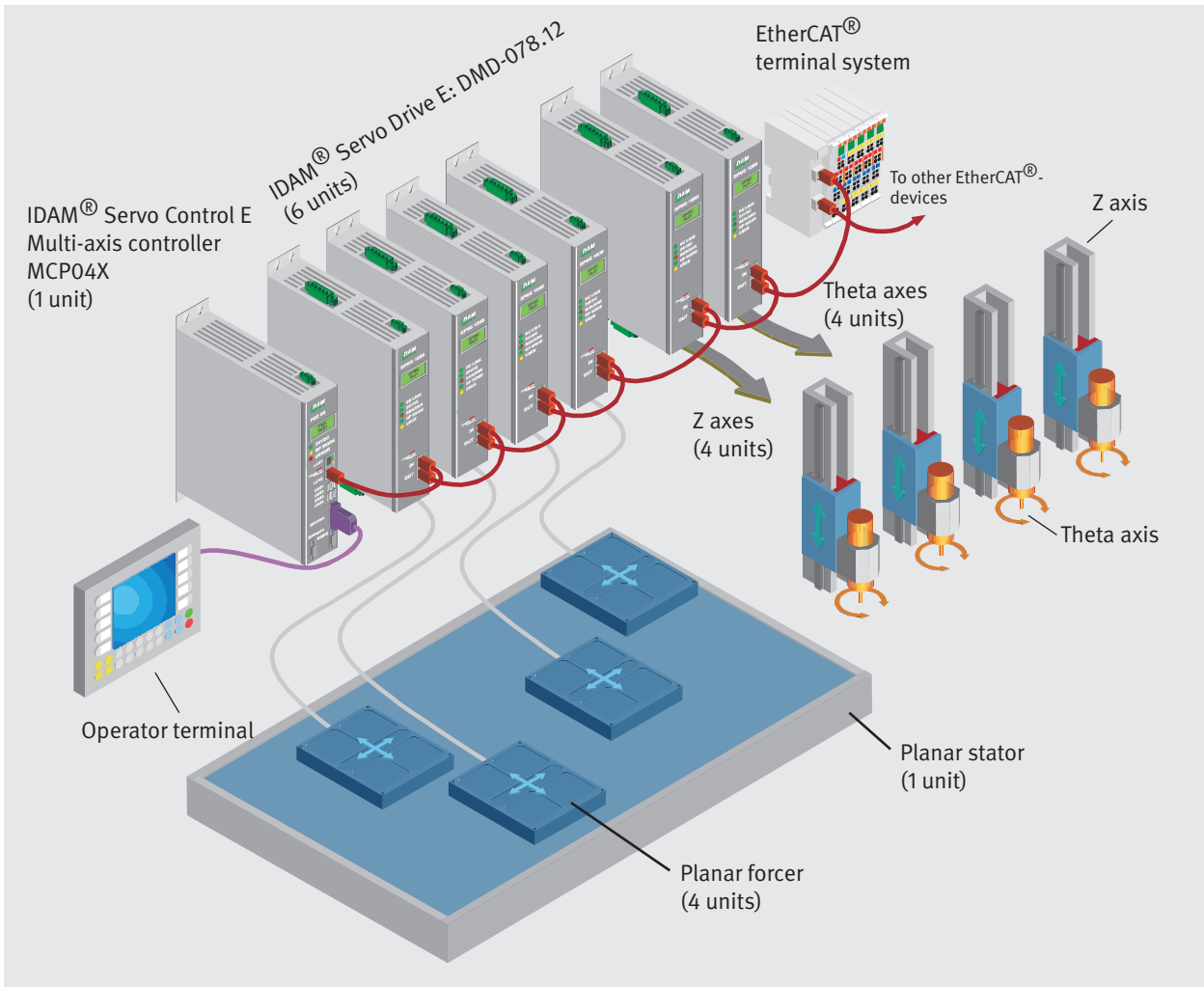
■ Technical Specifications

Power Unit	Unit	Value
External fuse for DC link input	A	16
DC link voltage	V_{DC}	24 ... 120
PWM frequency	kHz	20
Maximum peak load current per phase (1 s)	A_{rms}	10
	A_{peak}	15
Maximum continuous load current per phase (I_N @ 40 °C ambient; reduction 1,5% per °C)	A_{rms}	7
Auxiliary Power Supply	Unit	Value
Supply voltage	V_{DC}	$24 \pm 20\%$
Current consumption during operation	A	0.5 (externally fused)
Thermal overload protection	Unit	Value
Number of feedback signals		1 line for KTY-84 1 line for PTC quadruple
ADC resolution	Bit	12
Digital I/O	Unit	Value
Number of free configurable I/O		8
Number of dedicated IN		2
Output switching voltage	V_{DC}	24 (derived from auxiliary supply)
Continuous switching current	A	0.4
Peak switching current	A	0.6

■ Technical Specifications

Position Encoder HALL-IN Differential signal, voltage type, sin/cos without index	Unit	Value
Number of encoders		3
Input voltage	V _{pp}	1.0 ± 0.5
ADC resolution	Bit	14
Maximum input frequency	kHz	16
Position Encoder MS-OPTICAL-IN Differential signal, voltage type, sin/cos and reference signals	Unit	Value
Number of encoders		3
Input voltage	V _{pp}	1.0 ± 0.2
ADC resolution	Bit	12
Maximum input frequency	kHz	100
Reference signal conditioning		Analogue comparator
Field Bus Interface		Value
Type		EtherCAT®
Transfer rate		100 BASE TX
Transmission protocol		Product specific PDO (process data objects) and service data objects
Mechanical Dimensions (This product is intended for panel mounting.)	Unit	Value
Installation space (height x width x depth, incl. mounting plates)	mm	310 x 60 x 244
Total weight	kg	2.4

System Configuration (Example)

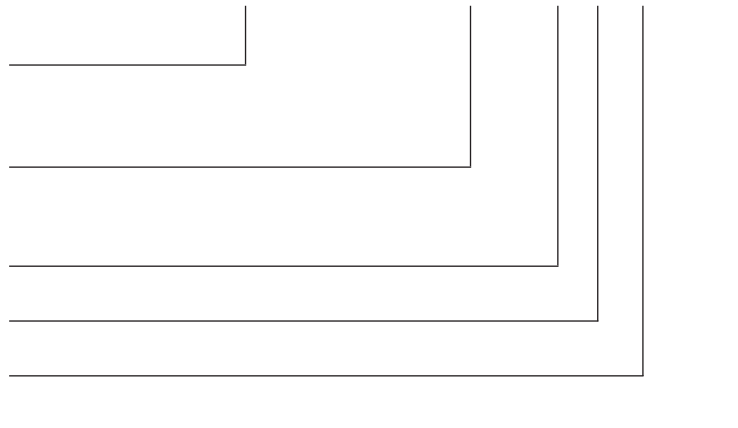


Example with 4 planar forcers, 4 multi-axis systems (4 Z axes and 4 Theta axes), 6 DMD-078.12 and 1 motion controller MCP04X

Type Designation

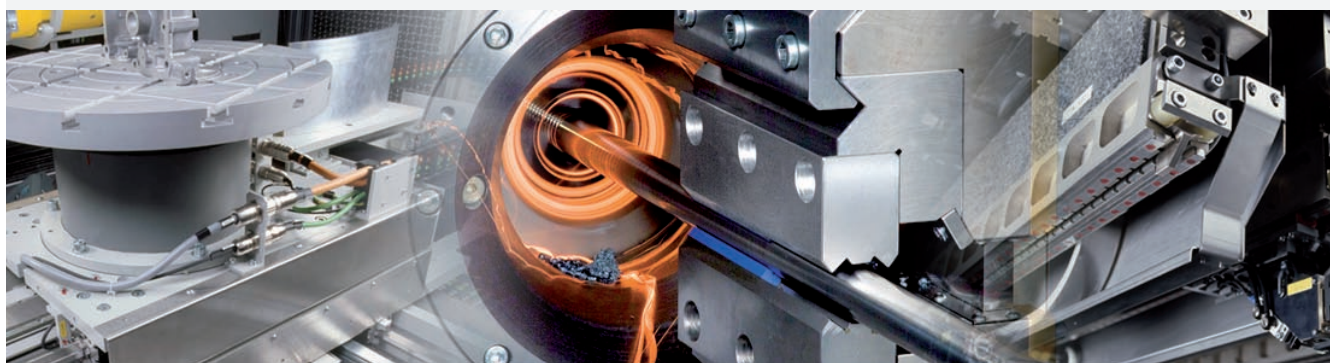
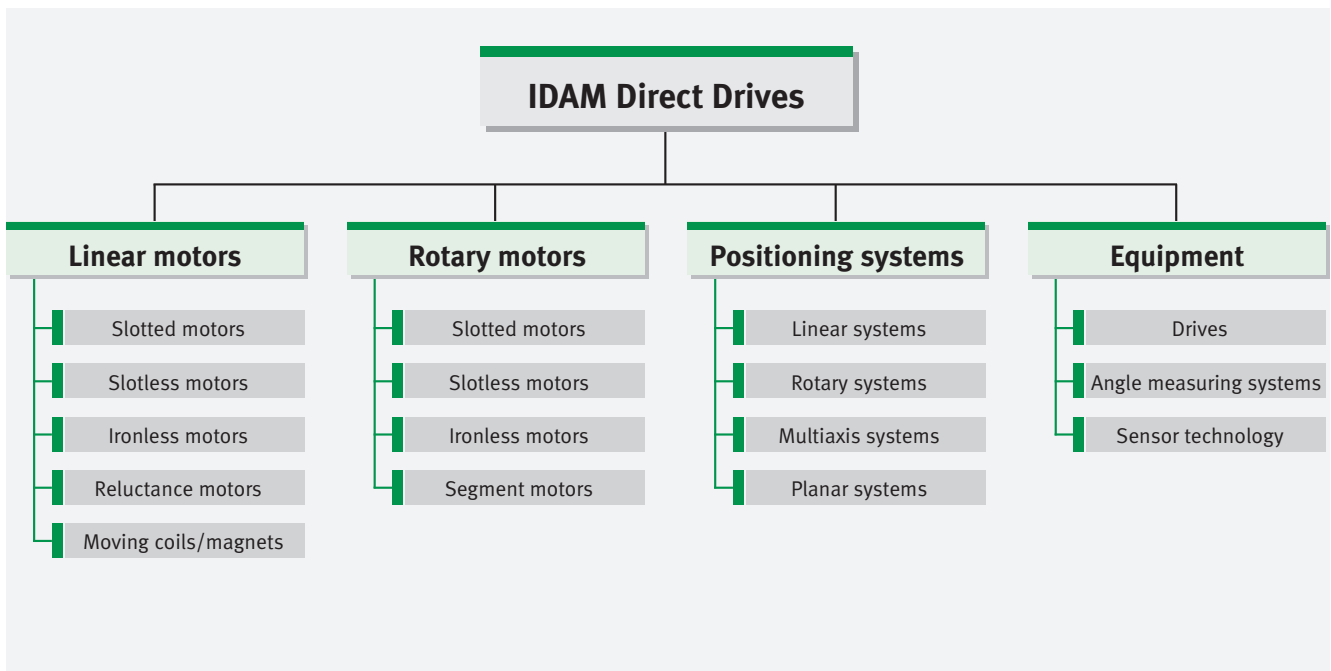
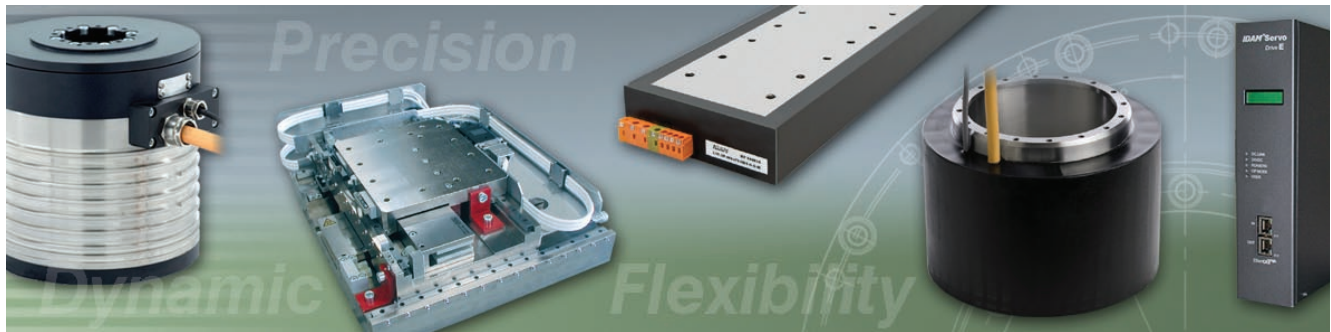
IDAM[®] Servo Drive E - DMD - 07 8.12 <version>

- Series
- IDAM[®] Servo Drive E
- Type, design
- DMD - Digital Motor Drive
- Continuous current (rms) per phase
- Number of controllable phases
- Maximum DC link voltage x 10
- Customer-specific version



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The Perfect Drive For Every Application.



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